

Bianchi Melosi Model

Appendix B of Cho and Moreno(2019,working paper) entitled "Has the Fiscal Policy Saved the Great Recession?" examines determinacy of the model of the Bianchi and Melosi(2019,AER in the mean-square stability sense. This note explains how to rewrite the original model ignoring exogenous shocks that do not affect determinacy properties.

A. Original Bianchi Melosi Model

$$\tilde{\pi}_t = \beta E_t \pi_{t+1} + \kappa \vartheta_1 \hat{y}_t + \kappa \vartheta_2 \hat{y}_{t-1}, \quad (1)$$

$$(1 + \Phi M_a^{-1}) \hat{y}_t = E_t y_{t+1} + \Phi M_a^{-1} \hat{y}_{t-1} - (1 - \Phi M_a^{-1})(\hat{R}_t - E_t \tilde{\pi}_{t+1}) \quad (2)$$

$$+ (1 - \Phi M_a^{-1})[(1 - \rho_d) d_t - \bar{d}_{\xi_t^d} + E_{\xi_t^d} \bar{d}_{\xi_{t+1}^d}] \quad (3)$$

$$\begin{aligned} \tilde{R}_t = & (1 - Z_{\xi_t^d}) \left[\rho_{R, \xi_t^d} \tilde{R}_{t-1} + (1 - \rho_{R, \xi_t^d})(\psi_{\pi, \xi_t^p} \tilde{\pi}_t + \psi_{y, \xi_t^p}(\hat{y}_t - \hat{y}_t^*)) \right] \\ & + Z_{\xi_t^d} \rho_{R, Z} \tilde{R}_{t-1} \end{aligned} \quad (5)$$

$$\tilde{R}_t = E_t[\tilde{R}_{t,t+1}^m] \quad (6)$$

$$\tilde{R}_{t-1,t}^m = R^{-1} \rho \tilde{P}_t^m - \tilde{P}_{t-1}^m \quad (7)$$

$$\vartheta_1 \hat{y}_t^* = \vartheta_2 \hat{y}_{t-1}^* \quad (8)$$

$$\tilde{b}_t^m = \beta^{-1} \tilde{b}_{t-1}^m + b^m \beta^{-1} \left[\hat{R}_{t-1,t}^m - \tilde{\pi}_t - \hat{y}_t + \hat{y}_{t-1} \right] - \tilde{\tau}_t + \tilde{tr}_t \quad (9)$$

$$\tilde{\tau}_t = \rho_{\tau, \xi_t^p} \tilde{\tau}_{t-1} + (1 - \rho_{\tau, \xi_t^p}) \left[\delta_{b, \xi_t^p} \tilde{b}_{t-1}^m + \delta_e \tilde{tr}_t^* + \delta_y (\hat{y}_t - \hat{y}_t^*) \right] \quad (10)$$

$$\tilde{tr}_t = \rho_{tr} \tilde{tr}_{t-1} + (1 - \rho_{tr}) \phi_y (\hat{y}_t - \hat{y}_t^*) \quad (11)$$

$$[\xi_t^p, \xi_t^d] = [M, h] = \{[Z, l], [M, h], [F, h], \} = \{1, 2, 0\} \quad (12)$$

$$P\{1, 2, 0\} = \begin{bmatrix} p_{hh} p_{MM} & p_{hh}(1 - p_{FF}) & (1 - p_{ll}) p_{ZM} \\ p_{hh}(1 - p_{MM}) & p_{hh} p_{FF} & (1 - p_{ll})(1 - p_{ZM}) \\ (1 - p_{hh}) & 1 - p_{hh} & p_{ll} \end{bmatrix}' \quad (13)$$

The model is simplified by eliminating $\tilde{P}_t^m, \tilde{R}_{t,t+1}^m, \hat{y}_t^*, d_t, \bar{d}_{\xi_t^d}$ further.

$$\tilde{\pi}_t = \beta E_t \pi_{t+1} + \kappa \vartheta_1 \hat{y}_t + \kappa \vartheta_2 \hat{y}_{t-1}, \quad (14)$$

$$(1 + \Phi M_a^{-1}) \hat{y}_t = E_t y_{t+1} + \Phi M_a^{-1} \hat{y}_{t-1} - (1 - \Phi M_a^{-1})(\hat{R}_t - E_t \tilde{\pi}_{t+1}) \quad (15)$$

$$\begin{aligned} \tilde{R}_t = & (1 - Z_{\xi_t^d}) \left[\rho_{R, \xi_t^d} \tilde{R}_{t-1} + (1 - \rho_{R, \xi_t^d})(\psi_{\pi, \xi_t^p} \tilde{\pi}_t + \psi_{y, \xi_t^p} \hat{y}_t) \right] \\ & + Z_{\xi_t^d} \rho_{R, Z} \tilde{R}_{t-1} \end{aligned} \quad (17)$$

$$\tilde{b}_t^m = \beta^{-1} \tilde{b}_{t-1}^m + b^m \beta^{-1} \left[\hat{R}_{t-1,t}^m - \tilde{\pi}_t - \hat{y}_t + \hat{y}_{t-1} \right] - \tilde{\tau}_t + \tilde{tr}_t \quad (18)$$

$$\tilde{\tau}_t = \rho_{\tau, \xi_t^p} \tilde{\tau}_{t-1} + (1 - \rho_{\tau, \xi_t^p}) \left[\delta_{b, \xi_t^p} \tilde{b}_{t-1}^m + \delta_y \hat{y}_t \right] \quad (19)$$

$$\tilde{tr}_t = \rho_{tr} \tilde{tr}_{t-1} + (1 - \rho_{tr}) \phi_y \hat{y}_t \quad (20)$$

Parameters

	$s_t = 0$ $[\xi_t^p, \xi_t^d] = [Z, l]$	$s_t = 1$ $[\xi_t^p, \xi_t^d] = [M, h]$	$s_t = 2$ $[\xi_t^p, \xi_t^d] = [F, h]$
$\psi_\pi(s_t)$	0	$\psi_{\pi, \xi_t^p} = 1.6019$	$\psi_{\pi, \xi_t^p} = 0.6356$
$\psi_y(s_t)$	0	$\psi_{y, \xi_t^p} = 0.5065$	$\psi_{y, \xi_t^p} = 0.2709$
$\rho_R(s_t)$	0	$\rho_{R, \xi_t^p} = 0.8652$	$\rho_{R, \xi_t^p} = 0.6663$
$\delta_b(s_t)$	0	$\delta_{b, \xi_t^p} = 0.0712$	$\delta_{b, \xi_t^p} = 0$
$\rho_\tau(s_t)$	0	$\rho_{\tau, \xi_t^p} = 0.9652$	$\rho_{\tau, \xi_t^p} = 0.6874$
$Z_{\xi_t^d}(s_t)$	1	0	0

(21)

$$\beta = 0.9985, \kappa = 0.0073, \Phi = 0.8628, \gamma = 0.004185, \rho_{R,Z} = 0.2; \quad (22)$$

$$b^m = 0.2672 * 4, \rho_{\tau,Z} = 0.6874 \quad (23)$$

$$\rho_{tr} = 0.4599, \delta_y = 0.2766, \delta_e = 0.3661, \phi_y = -0.2910, \quad (24)$$

$$p_{ll} = 0.9306, p_{hh} = 0.9995, p_{MM} = p_{FF} = 0.9923, p_{ZM} = 0.9225 \quad (25)$$

where

$$\vartheta_1 = \frac{1}{1 - \Phi M_a^{-1}} + \frac{\alpha}{1 - \alpha}, \quad \vartheta_2 = \frac{\Phi M_a^{-1}}{1 - \Phi M_a^{-1}} \quad (26)$$

$$\mu = \frac{1}{1 + \Phi M_a^{-1}}, \quad \tilde{\varphi} = \frac{(1 - \Phi M_a^{-1})}{1 + \Phi M_a^{-1}} \quad (27)$$

$$M_a = \exp(\gamma) \quad (28)$$

B. Rewriting the model in our notation (1) Regime

$$P\{0, 1, 2\} = \begin{bmatrix} p_{ll} & (1 - p_{ll})p_{ZM} & (1 - p_{ll})(1 - p_{ZM}) \\ (1 - p_{hh}) & p_{hh}p_{MM} & p_{hh}(1 - p_{MM}) \\ (1 - p_{hh}) & p_{hh}(1 - p_{FF}) & p_{hh}p_{FF} \end{bmatrix} \quad (29)$$

$$s_t = [\xi_t^p, \xi_t^d] = [M, h] = \{[Z, l], [M, h], [F, h], \} = \{0, 1, 2\} \quad (30)$$

(2) Model

$$\tilde{\pi}_t = \beta E_t \pi_{t+1} + \kappa \vartheta_1 \hat{y}_t - \kappa \vartheta_2 \hat{y}_{t-1}, \quad (31)$$

$$\hat{y}_t = \mu E_t y_{t+1} + (1 - \mu) \hat{y}_{t-1} - \tilde{\varphi} (\hat{R}_t - E_t \tilde{\pi}_{t+1}) \quad (32)$$

$$\tilde{R}_t = (1 - Z_{\xi_t^d}) \left\{ \rho_R(s_t) \tilde{R}_{t-1} + (1 - \rho_R(s_t)) (\psi_\pi(s_t) \tilde{\pi}_t + \psi_y(s_t) \hat{y}_t) \right\} + Z_{\xi_t^d}(s_t) \rho_{R,Z} \tilde{R}_{t-1} \quad (33)$$

$$\tilde{b}_t^m = \beta^{-1} \tilde{b}_{t-1}^m + b^m \beta^{-1} \left[\tilde{R}_{t-1} - \tilde{\pi}_t - \hat{y}_t + \hat{y}_{t-1} \right] - \tilde{\tau}_t + \tilde{tr}_t \quad (34)$$

$$\tilde{\tau}_t = \rho_\tau(s_t) \tilde{\tau}_{t-1} + (1 - \rho_\tau(s_t)) \left[\delta_b(s_t) \tilde{b}_{t-1}^m + \delta_y \hat{y}_t \right] \quad (35)$$

$$\tilde{tr}_t = \rho_{tr} \tilde{tr}_{t-1} + (1 - \rho_{tr}) \phi_y \hat{y}_t \quad (36)$$

(3) In Matrix form

$$\begin{aligned}
 x_t &= [\tilde{\pi}_t \ \hat{y}_t \ \hat{R}_t \ \hat{b}_t^m \ \tilde{\tau}_t \ \tilde{tr}_t] \\
 B_0 &= \begin{bmatrix} 1 & -\kappa\vartheta_1 & 0 & 0 & 0 & 0 \\ 0 & 1 & \tilde{\varphi} & 0 & 0 & 0 \\ -(1-\rho_R(s_t))\psi_\pi(s_t) & -(1-\rho_R(s_t))\psi_y(s_t) & 1 & 0 & 0 & 0 \\ \hat{b}^m\beta^{-1} & \hat{b}^m\beta^{-1} & 0 & 1 & 1 & -1 \\ 0 & -(1-\rho_\tau(s_t))\delta_y & 0 & 0 & 1 & 0 \\ 0 & -(1-\rho_{tr})\phi_y & 0 & 0 & 0 & 1 \end{bmatrix}, A_0 = \\
 &\begin{bmatrix} \beta & 0 & 0 & 0 & 0 & 0 \\ \tilde{\varphi} & \mu & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \\
 B_1 &= \begin{bmatrix} 0 & \kappa\vartheta_2 & 0 & 0 & 0 & 0 \\ 0 & 1-\mu & 0 & 0 & 0 & 0 \\ 0 & 0 & (1-Z_{\xi_t^d})\rho_R(s_t) + Z_{\xi_t^d}(s_t)\rho_{R,Z} & 0 & 0 & 0 \\ 0 & \hat{b}^m\beta^{-1} & \hat{b}^m\beta^{-1} & \beta^{-1} & 0 & 0 \\ 0 & 0 & 0 & (1-\rho_\tau(s_t))\delta_b(s_t) & \rho_\tau(s_t) & 0 \\ 0 & 0 & 0 & 0 & 0 & \rho_{tr} \end{bmatrix}
 \end{aligned}$$